

#### Teledyne e2v

## CX1151G **Hydrogen Thyratron**

The data to be read in conjunction with the Hydrogen Thyratron Preamble.

#### **ABRIDGED DATA**

Hydrogen-filled tetrode thyratron, featuring low jitter and low anode delay time drift. Suitable for use at high pulse repetition rates, in parallel for switching higher powers, or for switching long pulses. A reservoir operating from the cathode heater supply is incorporated. The tube is flange mounted with flexible lead connections.

| Peak forward anode voltage | - | 25 kV max  |
|----------------------------|---|------------|
| Peak anode current         | - | 1.0 kA max |
| Average anode current      | - | 1.25 A max |

#### **GENERAL DATA**

#### **Electrical**

| Cathode (connected internally to mid-point of      | - | Oxide coated         |
|--|---|----------------------|
| Heater voltage                                     | - | 6.3 +0.2 V<br>-0.3 V |
| Heater current                                     | - | 22 A                 |
| Tube heating time (minimum)                        | - | 5.0 min              |
| Inter-electrode capacitances                       |   |                      |
| Anode to grid 2 (grid 1 and cathode                | - | 13 pF                |
| Anode to grid 1 (grid 2 and cathode not            | - | 7.5 pF               |
| Anode to cathode (grid 1 and grid 2 not connected) | - | 26 pF                |

#### Mechanical

| Overall length                 | - | 301.0 mm (11.850 inches) max   |
|--------------------------------|---|--------------------------------|
| Overall diameter               | - | 84.12 mm (3.312 inches) max    |
| Net weight                     | - | 0.7 kg (1.5 pounds)<br>approx. |
| Mounting position (see note 1) | - | Any                            |
| Top cap (see note 2)           | - | BS448-CT3                      |



Cooling Natural

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#### **PULSE MODULATOR SERVICE**

## MAXIMUM AND MINIMUM RATINGS (Absolute values)

| Anode  |   | Min | Max                     |           |
|--|---|-----|-------------------------|-----------|
| Peak forward anode voltage (see note 3)                          |   | -   | 25                      | kV        |
| Peak inverse anode voltage (see note 4)                          |   | -   | 25                      | kV        |
| Peak anode current   |   | -   | 1.0                     | kA        |
| Peak anode current (pulse repetition rate limited to 60 pps max) | - | -   | 2.0                     | kA        |
| Average anode current  |   | -   | 1.25                    | Α         |
| Rate of rise of anode current (see note 5)                       |   | -   | 5.0                     | kA/µs     |
| Anode heating factor   |   | -   | 14 x<br>10 <sup>9</sup> | VApp<br>s |
|  |   |     |                         |           |

| Grid 2   | Min | Max  |       |
|--|-----|------|-------|
| Unloaded grid 2 drive pulse voltage (see note 6) | 300 | 1000 | V     |
| Grid 2 pulse duration                            | 1.0 | -    | μs    |
| Rate of rise of grid 2 pulse (see note 5)        | 1.0 | -    | kV/μs |
| Grid 2 pulse delay                               | 0.5 | 3.0  | μs    |
| Peak inverse grid 2 voltage                      | -   | 450  | V     |
| Loaded grid 2 bias voltage                       | -50 | -150 | V     |
| Forward impedance of grid 2 drive circuit        | 50  | 800  | Ω     |
|  |     |      |       |

| Grid 1 – DC Primed (see note 7)    | Min | Max |    |
|------------------------------------|-----|-----|----|
| DC grid 1 unloaded priming voltage | 75  | 150 | V  |
| DC grid 1 priming current          | 50  | 100 | mA |

| Grid 1 – Pulsed                                  | Min        | Max  |           |
|--|------------|------|-----------|
| Unloaded grid 1 drive pulse voltage (see note 6) | 300        | 1000 | V         |
| Grid 1 pulse duration                            | 2.0        | -    | μs        |
| Rate of rise of grid 1 pulse (see note 5)        | 1.0        | -    | kV/μ<br>s |
| Peak inverse grid 1 voltage                      | -          | 450  | V         |
| Loaded grid 1 bias voltage                       | See note 8 |      |           |
| Peak grid 1 drive current                        | 0.3        | 1.0  | Α         |

| Cathode           | Min | Max  |     |
|-------------------|-----|------|-----|
|                   |     | +0.2 | V   |
| Heater voltage    | 6.3 | -0.3 | V   |
| Tube heating time | 5.0 | -    | min |

| Environmental       | Min | Max             |          |
|---------------------|-----|-----------------|----------|
| Ambient temperature | 50  | +90             | °C       |
| Altitude            | · - | 3<br>10,00<br>0 | km<br>ft |

## **CHARACTERISTICS**

|   | Min                 | Iур  | мах  |    |
|---|---------------------|------|------|----|
| Critical DC anode voltage for conduction (see note 9) | -                   | 0.5  | 2.0  | kV |
| Anode delay time (see notes 9 and 10)                 | -                   | 0.15 | 0.25 | μs |
| Anode delay time drift (see notes 9 and 11)           | -                   | 20   | 50   | ns |
| Time jitter (see note 9) .                            | -                   | 5.0  | 10.0 | ns |
| Recovery time .                                       | . See graph, page 4 |      |      |    |
| Heater current (at 6.3 V)                             | 18                  | 22   | 25   | Α  |

# RATINGS FOR SINGLE-SHOT OR CROWBAR SERVICE (See note 7)

| DC forward anode voltage                   | - | 25 kV max              |
|--|---|------------------------|
| Peak anode current                         | - | 15 kA max              |
| Product of peak current and pulse duration | - | 0.6 A.s max            |
| Repetition frequency                       | - | 1 pulse per 10s<br>max |

#### **NOTES**

- 1. Clamping is only permissible by the base.
- 2. A large area anode connector, e2v technologies type MA360, is recommended.
- The maximum permissible peak forward voltage for instantaneous starting is 20 kV and there must be no overshoot.
- 4. The peak inverse voltage must not exceed 10 kV for the first 25  $\mu$ s after the anode pulse.
- 5. This rate of rise refers to that part of the leading edge of the pulse between 25% and 75% of the pulse amplitude.
- 6. Measured with respect to cathode. In certain cases the maximum drive pulse voltage may be exceeded without damage to the tube; a maximum value of 2.5 kV is then recommended. When grid 1 is pulse driven, the last 0.25 μs of the top of the grid 1 pulse must overlap the corresponding first 0.25 μs of the top of the delayed grid 2 pulse.
- 7. When DC priming is used on grid 1, a negative bias of 100 to 200 V must be applied to grid 2 to ensure anode voltage hold-off. DC priming is recommended for crowbar service.
- 8. DC negative bias voltages must not be applied to grid 1. When grid 1 is pulse driven, the potential of grid 1 may vary between -10 and +5 V with respect to cathode potential during the period between the completion of recovery and the commencement of the succeeding grid pulse.
- 9. Typical figures are obtained on test using conditions of minimum grid drive. Improved performance can be expected by increasing the grid drive.
- 10.The time interval between the instant at which the rising unloaded grid 2 pulse reaches 25% of its pulse amplitude and the instant when anode conduction takes place.
- 11. The drift in delay time over a period from 10 seconds to 10 minutes after reaching full voltage.

#### **HEALTH AND SAFETY HAZARDS**

e2v technologies thyratrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. e2v technologies does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipment incorporating e2v technologies devices and in operating manuals.



#### High Voltage

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access door open.

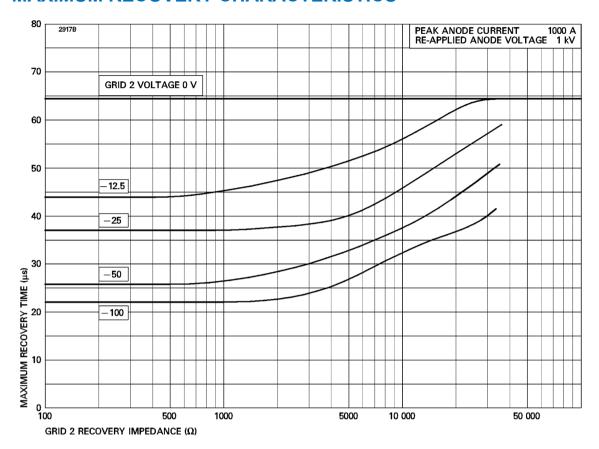


#### X-Ray Radiation

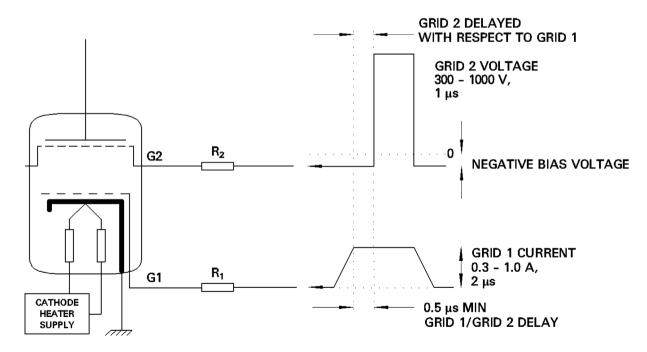
All high voltage devices produce X-rays during operation and may require shielding. The X-ray radiation from hydrogen thyratrons is usually reduced to a safe level by enclosing the equipment or shielding the thyratron with at least 1.6 mm (1/16 inch) thick steel panels.

Users and equipment manufacturers must check the radiation level under their maximum operating conditions.

#### MAXIMUM RECOVERY CHARACTERISTICS



#### **SCHEMATIC DIAGRAM**



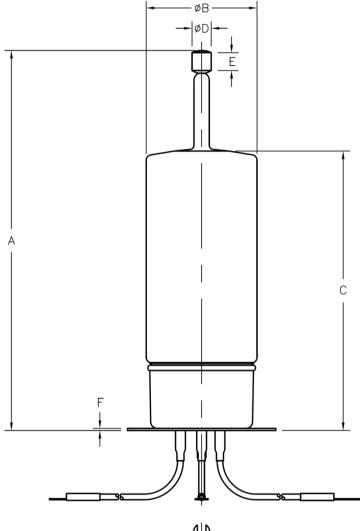
#### RECOMMENDED GRID AND CATHODE CONNECTIONS

- R<sub>1</sub> = Grid 1 series resistor. 12 W vitreous enamelled wirewound is recommended, of an impedance to match the grid 1 drive pulse circuit.
- R<sub>2</sub> = Grid 2 series resistor. 12 W vitreous enamelled wirewound is recommended, of an impedance to match the grid 2 drive pulse circuit.

Components R<sub>1</sub>, and R<sub>2</sub> should be mounted as close to the tube as possible.

## **OUTLINE**

## (All dimensions without limits are nominal)



| Millimetres    | Inches         |
|----------------|----------------|
| 288.00 ± 13.00 | 11.339 ± 0.512 |
| 84.12 max      | 3.312 max      |
| 216.00 ± 13.00 | 8.500 ± 0.512  |
| 14.38 ± 0.18   | 0.566 ± 0.008  |
| 12.70 min      | 0.500 min      |
| 1.60           | 0.063          |
| 216.00 min     | 8.500 min      |
| 6.35           | 0.250          |
| 111.10         | 4.375          |
| 95.25          | 3.750          |
| 6.50           | 0.256          |
|                |                |

dimensions have been derived millimetres

#### **Itline Notes**

The recommended hole in the mounting plate is 76 mm (3.0 inches) diameter.

A minimum clearance of 44.45 mm (1.75 inches) must be allowed below the mounting surface.

The mounting flange is the cathode connection and this is connected internally to the midpoint of the heater.

